

Solutions:

Homework Set 1

Due August 24, 2020

1. Consider the 2x2 matrices:

$$\mathbb{1} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad \sigma_x = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \quad \sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}, \quad \sigma_z = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \quad (1)$$

The three matrices $\sigma_x, \sigma_y,$ and σ_z are called the *Pauli matrices*, which can also be denoted $\sigma_1, \sigma_2, \sigma_3,$ respectively

(a) Show that

$$\sigma_i \sigma_j = \delta_{ij} + i \epsilon_{ijk} \sigma_k, \quad (2)$$

with $i \in \{1, 2, 3\}$. Here δ_{ij} is understood to be multiplied by $\mathbb{1}$, we use the summation convention (repeated indices k are summed) and ϵ_{ijk} is the completely antisymmetric Levi-Civita symbol.

A simple way to show it is to directly multiply each pair of matrices to see

$$\sigma_1 \sigma_1 = \sigma_2 \sigma_2 = \sigma_3 \sigma_3 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = \mathbb{1} \quad (3)$$

$$\sigma_1 \sigma_2 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix} = i \sigma_3 \quad (4)$$

$$\sigma_1 \sigma_3 = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix} = -i \sigma_2 \quad (5)$$

$$\sigma_2 \sigma_3 = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} = i \sigma_1 \quad (6)$$

etc.

(b) Consider a vector operator — that is, a set of operators $\mathbf{A} = (A_x, A_y, A_z)$, where A_x, A_y, A_z are operators.

Given two vector operators \mathbf{A}, \mathbf{B} that commute with $\boldsymbol{\sigma}$ but not each other, use Eq. (2) to show that

$$(\boldsymbol{\sigma} \cdot \mathbf{A})(\boldsymbol{\sigma} \cdot \mathbf{B}) = \mathbf{A} \cdot \mathbf{B} + i\boldsymbol{\sigma} \cdot (\mathbf{A} \times \mathbf{B}), \quad (7)$$

where

$$\boldsymbol{\sigma} = \sigma_x \hat{x} + \sigma_y \hat{y} + \sigma_z \hat{z}, \quad (8)$$

and two vector operators commute if all their components commute.

Note that in general, $\mathbf{A} \cdot \mathbf{B} \neq \mathbf{B} \cdot \mathbf{A}$, and $\mathbf{A} \times \mathbf{B} \neq -\mathbf{B} \times \mathbf{A}$

$$(\boldsymbol{\sigma} \cdot \mathbf{A})(\boldsymbol{\sigma} \cdot \mathbf{B}) = \sigma_i A_i \sigma_j B_j = \sigma_i \sigma_j A_i B_j \quad (9)$$

$$= (\delta_{ij} + i\epsilon_{ijk} \sigma_k) A_i B_j \quad (10)$$

$$= A_i B_i + i\sigma_k (\epsilon_{ijk} A_i B_j) \quad (11)$$

$$= \mathbf{A} \cdot \mathbf{B} + i\boldsymbol{\sigma} \cdot (\mathbf{A} \times \mathbf{B}), \quad (12)$$

(c) Let \hat{n} be an arbitrary unit vector and θ an arbitrary angle. Show that

$$\exp(-i\theta \boldsymbol{\sigma} \cdot \hat{n}) = \mathbb{1} \cos \theta - i(\boldsymbol{\sigma} \cdot \hat{n}) \sin \theta \quad (13)$$

An exponential of a matrix (or any operator) is defined by its Taylor series

$$\exp(-i\theta \boldsymbol{\sigma} \cdot \hat{n}) = \mathbb{1} - i\theta(\boldsymbol{\sigma} \cdot \hat{n}) - \frac{\theta^2}{2}(\boldsymbol{\sigma} \cdot \hat{n})(\boldsymbol{\sigma} \cdot \hat{n}) + \frac{i\theta^3}{3!}(\boldsymbol{\sigma} \cdot \hat{n})^3 + \dots \quad (14)$$

From the previous result we know that

$$(\boldsymbol{\sigma} \cdot \hat{n})(\boldsymbol{\sigma} \cdot \hat{n}) = \hat{n} \cdot \hat{n} + i\boldsymbol{\sigma} \cdot (\hat{n} \times \hat{n}) \quad (15)$$

$$= 1 + 0 \quad (16)$$

$$= \mathbb{1} \quad (17)$$

So

$$(\boldsymbol{\sigma} \cdot \hat{n})^3 = (\boldsymbol{\sigma} \cdot \hat{n}) \quad (18)$$

$$(\boldsymbol{\sigma} \cdot \hat{n})^4 = \mathbb{1} \quad (19)$$

$$(\boldsymbol{\sigma} \cdot \hat{n})^5 = (\boldsymbol{\sigma} \cdot \hat{n}) \quad (20)$$

$$\vdots \quad (21)$$

or

$$(\boldsymbol{\sigma} \cdot \hat{n})^{2m} = \mathbb{1}, \quad m \in \{0, 1, 2, 3, \dots\} \quad (22)$$

$$(\boldsymbol{\sigma} \cdot \hat{n})^{2m+1} = (\boldsymbol{\sigma} \cdot \hat{n}) \quad (23)$$

So the exponential is

$$\exp(-i\theta \boldsymbol{\sigma} \cdot \hat{n}) = \mathbb{1} \left(1 - \frac{\theta^2}{2!} + \frac{\theta^4}{4!} - \dots \right) - (\boldsymbol{\sigma} \cdot \hat{n}) \left(\theta - \frac{\theta^3}{3!} + \dots \right) \quad (24)$$

$$= \mathbb{1} \cos \theta - i(\boldsymbol{\sigma} \cdot \hat{n}) \sin \theta \quad (25)$$

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2. (a) Consider two operators A, B that do not commute. Show that

$$e^A B e^{-A} = B + [A, B] + \frac{1}{2!}[A, [A, B]] + \frac{1}{3!}[A, [A, [A, B]]] + \dots \quad (26)$$

Hint: Replace A by λA , where λ is a parameter, and let the left-hand side be $F(\lambda)$. Find a differential equation satisfied by $F(\lambda)$ and solve it. Alternatively, expand $F(\lambda)$ in a Taylor series in λ . At the end, set $\lambda = 1$.

Let $F(\lambda) \equiv e^{\lambda A} B e^{-\lambda A}$. Then

$$\frac{dF}{d\lambda} = e^{\lambda A} A B e^{-\lambda A} - e^{\lambda A} B A e^{-\lambda A} \quad (27)$$

$$= e^{\lambda A} (A B - B A) e^{-\lambda A} \quad (28)$$

$$= e^{\lambda A} [A, B] e^{-\lambda A} \quad (29)$$

$$\frac{dF^2}{d\lambda^2} = e^{\lambda A} [A, [A, B]] e^{-\lambda A} \quad (30)$$

$$\frac{dF^3}{d\lambda^3} = e^{\lambda A} [A, [A, [A, B]]] e^{-\lambda A} \quad (31)$$

$$\vdots \quad (32)$$

$$\left. \frac{dF^n}{d\lambda^n} \right|_{\lambda=0} = \underbrace{[A, [A, [A, \dots, B]] \dots]}_{n \text{ times}} \quad (33)$$

So, finally, we can write the Taylor series of F around $\lambda = 0$ as

$$F(\lambda) = \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} \left. \frac{dF^n}{d\lambda^n} \right|_{\lambda=0} \quad (34)$$

$$= \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} \underbrace{[A, [A, [A, \dots, B]] \dots]}_{n \text{ times}} \quad (35)$$

$$= B + \lambda [A, B] + \frac{\lambda^2}{2!} [A, [A, B]] + \frac{\lambda^3}{3!} [A, A, [A, B]] + \dots \quad (36)$$

(b) Let $A(t)$ be an operator that depends on time. Derive the following operator identity:

$$\frac{d(e^A)}{dt} e^{-A} = \sum_{n=0}^{\infty} \frac{1}{(n+1)!} L_A^n \left(\frac{dA}{dt} \right), \quad (37)$$

where

$$L_A(X) = [A, X], \quad L_A^2(X) = [A, [A, X]], \quad \dots, \quad (38)$$

where X is an arbitrary operator. Also, $L_A^0 = X$. Do not assume that A commutes with dA/dt .

We can again derive a differential equation. Define

$$F(\alpha, t) = \frac{d(e^{\alpha A(t)})}{dt} e^{-\alpha A(t)} \quad (39)$$

Then

$$\frac{\partial F}{\partial \alpha} = \alpha \frac{d}{dt} (e^{\alpha A(t)} A(t)) e^{-\alpha A(t)} - \alpha \frac{d(e^{\alpha A(t)})}{dt} A(t) e^{-\alpha A(t)} \quad (40)$$

$$= \alpha \frac{d(e^{\alpha A})}{dt} A e^{-\alpha A} + \alpha e^{\alpha A} \frac{dA}{dt} e^{-\alpha A} - \alpha \frac{d(e^{\alpha A})}{dt} A e^{-\alpha A} \quad (41)$$

$$= \alpha e^{\alpha A} \frac{dA}{dt} e^{-\alpha A} \quad (42)$$

Using the previous result with $B = dA/dt$, we can write

$$\frac{\partial F}{\partial \alpha} = \sum_{n=0}^{\infty} \frac{\alpha^n}{n!} \underbrace{[A, [A, [A, \dots, \frac{dA}{dt}]]}_{n \text{ times}} \dots \quad (43)$$

$$= \sum_{n=0}^{\infty} \frac{\alpha^n}{n!} L_A^n \left(\frac{dA}{dt} \right) \quad (44)$$

If we note that $F(0, t) = 0$, we can write

$$F(\alpha, t) = \int_0^\alpha d\alpha' \frac{\partial F}{\partial \alpha'}(\alpha', t) \quad (45)$$

$$= \sum_{n=0}^{\infty} \frac{\alpha^{n+1}}{(n+1)!} L_A^n \left(\frac{dA}{dt} \right) \quad (46)$$

We can set $\alpha = 1$ to obtain the final result

$$F(1, t) = \frac{d(e^A)}{dt} e^{-A} = \sum_{n=0}^{\infty} \frac{1}{(n+1)!} L_A^n \left(\frac{dA}{dt} \right). \quad (47)$$

3. (a) If A and B are square matrices, show that

$$\text{tr}(AB) = \text{tr}(BA) \quad (48)$$

Show that this implies the cyclic property of the trace of an arbitrary number of matrices

$$\text{tr}(A_1 A_2 \dots A_n) = \text{tr}(A_n A_1 A_2 \dots A_{n-1}) = \text{tr}(A_{n-1} A_n A_1 A_2 \dots A_{n-2}) = \dots \quad (49)$$

In index notation

$$\text{tr}(AB) = \sum_i (AB)_{ii} \quad (50)$$

$$= \sum_{ij} A_{ij} B_{ji} \quad (51)$$

Each component of the matrix is an ordinary number that commutes, so

$$\text{tr}(AB) = \sum_{ij} B_{ji} A_{ij} \quad (52)$$

$$= \sum_j (BA)_{jj} \quad (53)$$

$$= \text{tr}(BA) \quad (54)$$

This works for any number of matrices. E.g.,

$$\text{tr}(ABCD) = \sum_{ijkl} A_{ij} B_{jk} C_{kl} D_{li} \quad (55)$$

$$= \sum_{ijkl} D_{li} A_{ij} B_{jk} C_{kl} = \text{tr}(DABC) \quad (56)$$

$$= \sum_{ijkl} C_{kl} D_{li} A_{ij} B_{jk} = \text{tr}(CDAB) \quad (57)$$

$$= \sum_{ijkl} B_{jk} C_{kl} D_{li} A_{ij} = \text{tr}(BCDA) \quad (58)$$

but only cyclic permutations. E.g.,

$$\text{tr}(ABCD) \neq \text{tr}(BACD), \quad (59)$$

etc.

(b) Show that $\text{tr} \sigma_i = 0$. Then use Eq. (2) to find a simple expression for $\text{tr}(\sigma_i \sigma_j)$

By inspection, the sum of the diagonal elements are zero,

$$\text{tr} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \text{tr} \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} = \text{tr} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} = 0 \quad (60)$$

From Eq. (2), we have

$$\text{tr}(\sigma_i \sigma_j) = \text{tr}(\mathbb{1} \delta_{ij} + i \epsilon_{ijk} \sigma_k) \quad (61)$$

$$= 2\delta_{ij}, \quad (62)$$

since $\text{tr}(\mathbb{1}) = 2$.

- (c) The set of four 2×2 matrices, $(\mathbb{1}, \boldsymbol{\sigma})$ form a basis in the space of 2×2 matrices. I.e., an arbitrary matrix M can be expressed as a linear combination of these four matrices:

$$M = a\mathbb{1} + \mathbf{b} \cdot \boldsymbol{\sigma}. \quad (63)$$

Find simple expressions for the expansion coefficients, a and $\mathbf{b} = (b_1, b_2, b_3)$. Do this by taking traces, or by multiplying by a Pauli matrix and then taking traces. Also show that M is Hermitian if and only if a, \mathbf{b} are real.

$$M = a\mathbb{1} + \mathbf{b} \cdot \boldsymbol{\sigma} \quad (64)$$

$$\text{tr}(M) = 2a \quad (65)$$

$$\implies a = \frac{1}{2} \text{tr}(M) \quad (66)$$

$$\text{tr}(\sigma_i M) = \text{tr}(a\sigma_i + b_j \sigma_i \sigma_j) \quad (67)$$

$$= 0 + 2b_j \delta_{ij} \quad (68)$$

$$\implies b_i = \frac{1}{2} \text{tr}(\sigma_i M) \quad (69)$$

Note that all the Pauli matrices are Hermitian: $\sigma_i^\dagger = \sigma_i$, and also the identity matrix. So the Hermitian conjugate of M is

$$M^\dagger = a^* \mathbb{1} + \mathbf{b}^* \cdot \boldsymbol{\sigma} \quad (70)$$

and

$$a^* = \frac{1}{2} \text{tr}(M^\dagger) \quad (71)$$

$$b_i^* = \frac{1}{2} \text{tr}(\sigma_i M^\dagger) \quad (72)$$

If $M = M^\dagger$, then $a = a^*$ and $b = b^*$, and also the converse.

- (d) Now suppose that M is nonzero in only one of the 4 components, where it has value 1. That is, let

$$M_{ij} = \delta_{ir} \delta_{js} \quad (73)$$

For some coordinate (r,s) .

Use this in Eq. (63) to find a nice expression for $(\sigma_m)_{ij}(\sigma_m)_{kl}$ (summing over all indices) in terms of Kronecker deltas.

We again write

$$M = a \mathbb{1} + \mathbf{b} \cdot \boldsymbol{\sigma} \quad (74)$$

with

$$a = \frac{1}{2} \text{tr}(M) \quad (75)$$

$$= \frac{1}{2} \sum_i M_{ii} \quad (76)$$

$$= \frac{1}{2} \sum_i \delta_{ir} \delta_{is} \quad (77)$$

$$= \frac{1}{2} \delta_{rs} \quad (78)$$

$$b_i = \frac{1}{2} \text{tr}(\sigma_i M) \quad (79)$$

$$= \frac{1}{2} \sum_{jk} (\sigma_i)_{jk} M_{kj} \quad (80)$$

$$= \frac{1}{2} \sum_{jk} (\sigma_i)_{jk} \delta_{kr} \delta_{js} \quad (81)$$

$$= \frac{1}{2} (\sigma_i)_{sr} \quad (82)$$

So

$$M = \frac{1}{2}\delta_{rs}\mathbb{1} + \frac{1}{2}\sum_m(\sigma_m)_{sr}\sigma_m \quad (83)$$

$$M_{ij} = \delta_{ir}\delta_{js} = \frac{1}{2}\delta_{rs}\delta_{ij} + \frac{1}{2}(\sigma_m)_{sr}(\sigma_m)_{ij} \quad (84)$$

and finally

$$(\sigma_m)_{sr}(\sigma_m)_{ij} = 2\delta_{ir}\delta_{js} - \delta_{rs}\delta_{ij} \quad (85)$$

or, changing indices,

$$(\sigma_m)_{ij}(\sigma_m)_{kl} = 2\delta_{kj}\delta_{li} - \delta_{ij}\delta_{kl}. \quad (86)$$
